

# Imaging Gradients

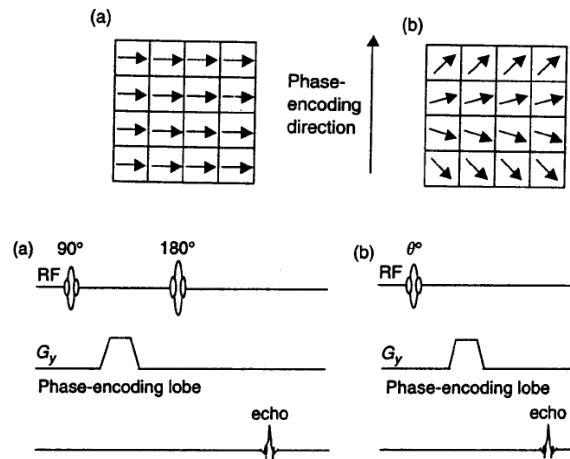
Nov2, 2005

Reference: Handbook of pulse sequences

## Phase-Encoding Gradients

- Spatial Localization in MRI employs both phase and frequency encoding.
- Phase encoding creates a linear spatial variation of the phase of the magnetization.
- Phase : angle made by the transverse magnetization vector with respect to some fixed axis in the transverse plane

# Phase Encoding



# Phase-Encoding

- Phase encoding must be applied before readout gradient
- Different phase variation is introduced by changing the area under the phase encoding gradient
- Phase encoding is used to spatially encode information orthogonal to the frequency-encoded direction

## Mathematical description

- For a  $y$  –phase encoding gradients  $G_y$

$$\omega = \gamma G_y y$$

$$\phi = \gamma y \int_0^T G_y(\tau) d\tau = 2\pi k_y y \quad (1)$$

- The effective magnetization  $M_p = M_x + iM_y$

$$S(k_y) = \int M_p(y) e^{-i\phi(y)} dy \quad (2)$$

## Phase-Encoding (cont'd)

- Transforming (2) to a discrete eq. using (1)

$$S(k_y) = \sum_{n=0}^{N-1} M_p(n\Delta y) e^{-2\pi i(n\Delta y)k_y} \quad (3)$$

- Repeat the phase encoding steps for  $N$  times
- For  $N$  phase encoding lines, the area covered in  $k$ -space is  $(N-1)\Delta k_y$

## Phase-Encoding (cont'd)

- For N phase-encoding step acquired sequentially starting at the top edge of k-space

$$k_y(m) = k_{y,\max} - m\Delta ky \quad m = 0, 1, \dots, N-1$$

$$k_{y,\max} = \frac{1}{2}(N-1)\Delta ky$$

$$\Rightarrow k_y(m) = \left(\frac{N-1}{2} - m\right)\Delta ky \quad (4)$$

The signal:

$$S(m) = \sum_{n=0}^{N-1} M_p(n\Delta y) e^{-2\pi i(n\Delta y)\left(\frac{N-1}{2} - m\right)\Delta ky} \quad m = 0, \dots, N-1 \quad (5)$$

## Phase-Encoding (cont'd)

$\Delta ky$  chosed based on the Nyquist criterion

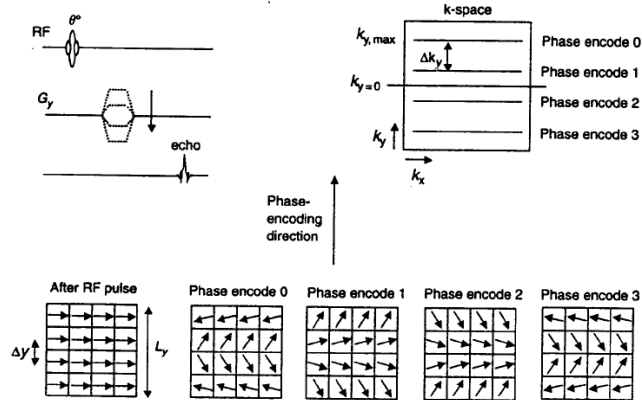
$$\Delta ky = \frac{1}{FOV_y} = \frac{1}{N\Delta y}$$

$$N\Delta k_y = \frac{1}{\Delta y}$$

equation 5 becomes

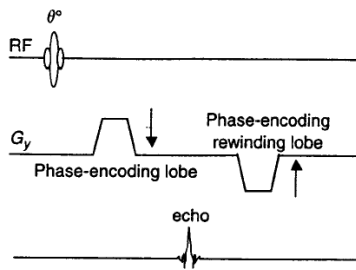
$$S(m) = \sum_{n=0}^{N-1} M_p(n\Delta y) e^{-\pi i n(N-1)/N} e^{-2\pi i m n / N} \quad (6)$$

# Gradient echo with four phase encoding steps



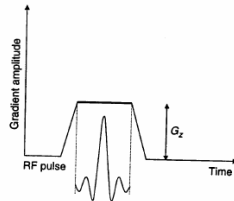
# Rephasing Lobe

- For each phase encoding step a rephaser with a negative area is applied



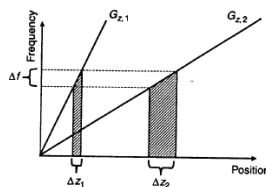
## Slice Selection Gradients

- Spatially selective RF pulses require a slice-selection gradient.
- The slice selection gradient is a constant gradient that is played concurrently with the selective RF pulse.



## Slice Selection Gradients

- A slice rephasing lobe generally follows the slice-selection gradient.
- The slice selection gradient translates the band of frequencies into the desired band of locations.
- Increasing the amplitude of the slice selection gradient decreases the thickness of the slice for a fixed RF bandwidth



## Mathematical description

$$f = \frac{\gamma}{2\pi} B \quad \text{applying the slice selection gradient } \vec{G}_z$$

$$f = \frac{\gamma}{2\pi} (B_0 + G_z \Delta z)$$

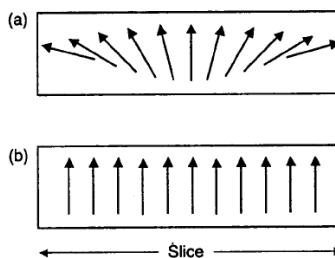
$$f_{rot} = \frac{\gamma}{2\pi} G_z \Delta z$$

$$\Delta z = \frac{2\pi \Delta f}{\gamma \vec{G}_z}$$

How can we obtain thinner slices??

## Slice Rephasing

- Rephasing lobe restores the signal



# Examples